## CLASSIFICATION OF AUTOREGRESSIVE TIME SERIES UNDER "OUTLIERS"

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## Abstract

The problem of robust classification of autoregressive time series under "outliers" considered and the asymptotic expansion of the risk of classification is constructed in the paper.

Let random time series  $X=(x_1,\ldots,x_n)\in\mathbf{R}^n$  of length n belonging to one of  $L(L\geq 2)$  classes  $\Omega_1,\ldots,\Omega_L$  with a priori probabilities  $\pi_1,\ldots,\pi_L(\pi_1+\ldots+\pi_L=1)$  is observed. A random time series from the class  $\Omega_i$  is described by the model of autoregression  $\mathrm{AR}(p)$  with observations errors:

$$y_t + \theta_{i1}y_{t-1} + \ldots + \theta_{ip}y_{t-p} = v_t,$$
 (1)

$$x_t = y_t + (1 + (K_i - 1)\eta_t^{(i)})\sigma\xi_t, \quad (i = \overline{1, L}; \ t = \overline{1, n}),$$
 (2)

where p is the order of autoregression;  $\theta_i = (\theta_{i1}, \dots, \theta_{ip})' \in \mathbb{R}^p$  — is the vector of autoregression coefficients (class i);  $v_t$  — is sequence of i.i.d. Gaussian random variables with zero mean and the variance  $B^2 < \infty$ ;  $\{\xi_t\}$  — is a sequence of i.i.d. random with p.d.f. f(x);  $\{\eta_t^{(i)}\}$  — is a sequence of i.i.d. Bernouli random variables:

$$\mathbf{P}\{\eta_t^{(i)} = 1\} = \varepsilon_i, \quad \mathbf{P}\{\eta_t^{(i)} = 0\} = 1 - \varepsilon_i, \quad 0 \le \varepsilon_i \le \varepsilon_+.$$
 (3)

Here  $\sigma > 0, K_i >> 1, \varepsilon_i, \varepsilon_+$  — are parameters of the model.

Ignoring of the "outliers" in model (1)—(3) leads to the fact, that the Bayesian decision rule  $d = d_o(X) : \mathbb{R}^n \to S = \{1, 2, \dots, L\}$ , wich minimizes risk at  $\varepsilon_+$  (absence distortions), looses its optimality under "outliers" presence  $\varepsilon_+ > 0$ .

In the paper the following topical problems are solved: robustness evaluation for traditional Bayesian decision rules under "outliers"; estimation of critical distortions level  $\varepsilon_+, K_i$ ; constuction robust decision rules  $d = d_*(X)$ .

Computer results are presented for Gaussian model of distortions:  $f(z) = n_1(z/0, 1)$ .