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# ДИФФЕРЕНЦИАЛЬНЫЕ УРАВНЕНИЯ И ОПТИМАЛЬНОЕ УПРАВЛЕНИЕ

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## DIFFERENTIAL EQUATIONS AND OPTIMAL CONTROL

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УДК 517.95

### НАЧАЛЬНО-КРАЕВАЯ ЗАДАЧА С НЕЛОКАЛЬНЫМ ГРАНИЧНЫМ УСЛОВИЕМ ДЛЯ НЕЛИНЕЙНОГО ПАРАБОЛИЧЕСКОГО УРАВНЕНИЯ С ПАМЯТЬЮ

А. Л. ГЛАДКОВ<sup>1)</sup>

<sup>1)</sup>Белорусский государственный университет, пр. Независимости, 4, 220030, г. Минск, Беларусь

Рассмотрено нелинейное параболическое уравнение с памятью  $u_t = \Delta u + au^p \int_0^t u^q(x, \tau) d\tau - bu^m$  для  $(x, t) \in \Omega \times (0, +\infty)$  с нелинейным нелокальным граничным условием  $\frac{\partial u(x, t)}{\partial \nu} \Big|_{\partial \Omega \times (0, +\infty)} = \int_{\Omega} k(x, y, t) u^l(y, t) dy$  и начальными данными  $u(x, 0) = u_0(x)$ ,  $x \in \Omega$ , где  $a, b, q, m, l$  – положительные постоянные;  $p \geq 0$ ;  $\Omega$  – ограниченная область в пространстве  $\mathbb{R}^n$  с гладкой границей  $\partial \Omega$ ;  $\nu$  – единичная внешняя нормаль к  $\partial \Omega$ . Неотрицательная непрерывная функция  $k(x, y, t)$  определена при  $x \in \partial \Omega$ ,  $y \in \bar{\Omega}$ ,  $t \geq 0$ , неотрицательная функция  $u_0(x) \in C^1(\bar{\Omega})$ , при этом она удовлетворяет условию  $\frac{\partial u_0(x)}{\partial \nu} = \int_{\Omega} k(x, y, 0) u_0^l(y) dy$  при  $x \in \partial \Omega$ . Рассмотрены классические решения.

Установлено существование локального максимального решения исходной задачи. Введены понятия верхнего и нижнего решений. Показано, что при выполнении определенных условий верхнее решение не меньше нижнего решения. Найдены условия положительности решений. Как следствие положительности решений и принципа сравнения решений доказана теорема единственности решения.

**Ключевые слова:** нелинейное параболическое уравнение; нелокальное граничное условие; существование решения; принцип сравнения.

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#### Автор:

Александр Львович Гладков – доктор физико-математических наук, профессор; заведующий кафедрой математической кибернетики механико-математического факультета.

#### Author:

Alexander L. Gladkov, doctor of science (physics and mathematics), full professor; head of the department of mathematical cybernetics, faculty of mechanics and mathematics.  
[gladkova@bsu.by](mailto:gladkova@bsu.by)

# INITIAL BOUNDARY VALUE PROBLEM WITH NONLOCAL BOUNDARY CONDITION FOR A NONLINEAR PARABOLIC EQUATION WITH MEMORY

A. L. GLADKOV<sup>a</sup>

<sup>a</sup>Belarusian State University, 4 Niezaliezhnasci Avenue, Minsk 220030, Belarus

We consider a nonlinear parabolic equation with memory  $u_t = \Delta u + au^p \int_0^t u^q(x, \tau) d\tau - bu^m$  for  $(x, t) \in \Omega \times (0, +\infty)$  under nonlinear nonlocal boundary condition  $\frac{\partial u(x, t)}{\partial \nu} \Big|_{\partial\Omega \times (0, +\infty)} = \int_{\Omega} k(x, y, t) u^l(y, t) dy$  and initial data  $u(x, 0) = u_0(x)$ ,  $x \in \Omega$ , where  $a, b, q, m, l$  are positive constants;  $p \geq 0$ ;  $\Omega$  is a bounded domain in  $\mathbb{R}^n$  with smooth boundary  $\partial\Omega$ ;  $\nu$  is unit outward normal on  $\partial\Omega$ . Nonnegative continuous function  $k(x, y, t)$  is defined for  $x \in \partial\Omega$ ,  $y \in \bar{\Omega}$ ,  $t \geq 0$ , nonnegative function  $u_0(x) \in C^1(\bar{\Omega})$ , while it satisfies the condition  $\frac{\partial u_0(x)}{\partial \nu} = \int_{\Omega} k(x, y, 0) u_0^l(y) dy$  for  $x \in \partial\Omega$ . In this paper we study classical solutions. We establish the existence of a local maximal solution of the original problem. We introduce definitions of a supersolution and a subsolution. It is shown that under some conditions a supersolution is not less than a subsolution. We find conditions for the positiveness of solutions. As a consequence of the positiveness of solutions and the comparison principle of solutions, we prove the uniqueness theorem.

**Keywords:** nonlinear parabolic equation; nonlocal boundary condition; existence of a solution; comparison principle.

## Introduction

In this paper we consider the initial boundary value problem for the nonlinear parabolic equation

$$u_t = \Delta u + au^p \int_0^t u^q(x, \tau) d\tau - bu^m, \quad x \in \Omega, \quad t > 0, \quad (1)$$

with nonlinear nonlocal boundary condition

$$\frac{\partial u(x, t)}{\partial \nu} = \int_{\Omega} k(x, y, t) u^l(y, t) dy, \quad x \in \partial\Omega, \quad t > 0, \quad (2)$$

and initial datum

$$u(x, 0) = u_0(x), \quad x \in \Omega, \quad (3)$$

where  $a, b, q, m, l$  are positive constants;  $p \geq 0$ ;  $\Omega$  is a bounded domain in  $\mathbb{R}^n$  ( $n \geq 1$ ) with smooth boundary  $\partial\Omega$ ;  $\nu$  is unit outward normal on  $\partial\Omega$ .

Throughout this paper we suppose that the functions  $k(x, y, t)$  and  $u_0(x)$  satisfy the following conditions:

$$k(x, y, t) \in C(\partial\Omega \times \bar{\Omega} \times [0, +\infty)), \quad k(x, y, t) \geq 0,$$

$$u_0(x) \in C^1(\bar{\Omega}), \quad u_0(x) \geq 0 \text{ in } \Omega, \quad \frac{\partial u_0(x)}{\partial \nu} = \int_{\Omega} k(x, y, 0) u_0^l(y) dy \text{ on } \partial\Omega.$$

Initial boundary value problems with nonlocal terms in parabolic equations or in boundary conditions have been considered in many papers (see, for example, [1–17] and the references therein). In particular, the initial boundary value problem (1)–(3) with  $a = 0$  was considered for  $b = b(x, t) \geq 0$  and  $b = b(x, t) \leq 0$  in publications [18; 19] and [20; 21] respectively. Problem (1)–(3) with  $p = 0$  and nonlocal boundary condition

$$u(x, t) = \int_{\Omega} k(x, y, t) u^l(y, t) dy, \quad x \in \partial\Omega, \quad t > 0, \quad (4)$$

was investigated in work [22].

The aim of this paper is to study problem (1)–(3) for any positive  $p, q, m$  and  $l$ . We prove existence of a local solution of problem (1)–(3). Comparison principle and the uniqueness of a solution are established. We show the nonuniqueness of solution of problem (1)–(3) with  $u_0(x) \equiv 0$  also.

### Local existence

In this section a local existence theorem for problem (1)–(3) will be proved. We begin with definitions of a supersolution, a subsolution and a maximal solution of problem (1)–(3). Let  $Q_T = \Omega \times (0, T)$ ,  $S_T = \partial\Omega \times (0, T)$ ,  $\Gamma_T = S_T \cup \bar{\Omega} \times \{0\}$ ,  $T > 0$ .

**Definition 1.** We say that a nonnegative function  $u(x, t) \in C^{2,1}(Q_T) \cap C^{1,0}(Q_T \cup \Gamma_T)$  is a supersolution of problem (1)–(3) in  $Q_T$  if

$$u_t \geq \Delta u + au^p \int_0^t u^q(x, \tau) d\tau - bu^m, \quad (x, t) \in Q_T, \quad (5)$$

$$\frac{\partial u(x, t)}{\partial \nu} \geq \int_{\Omega} k(x, y, t) u^l(y, t) dy, \quad (x, t) \in S_T, \quad (6)$$

$$u(x, 0) \geq u_0(x), \quad x \in \Omega, \quad (7)$$

and a nonnegative function  $u(x, t) \in C^{2,1}(Q_T) \cap C^{1,0}(Q_T \cup \Gamma_T)$  is a subsolution of problem (1)–(3) in  $Q_T$  if  $u \geq 0$  and it satisfies inequalities (5)–(7) in the reverse order. We say that  $u(x, t)$  is a solution of problem (1)–(3) in  $Q_T$  if  $u(x, t)$  is both a subsolution and a supersolution of problem (1)–(3) in  $Q_T$ .

**Definition 2.** We say that  $u(x, t)$  is a maximal solution of problem (1)–(3) in  $Q_T$  if for any other solution  $w(x, t)$  of problem (1)–(3) in  $Q_T$  the inequality  $w(x, t) \leq u(x, t)$  is satisfied for  $(x, t) \in Q_T \cup \Gamma_T$ .

Let  $\{\varepsilon_m\}$  be decreasing to zero a sequence such that  $0 < \varepsilon_m < 1$  and  $\varepsilon_m \rightarrow 0$  as  $m \rightarrow \infty$ . For  $\varepsilon = \varepsilon_m$ ,  $m = 1, 2, \dots$ , let  $u_{0\varepsilon}(x)$  be the functions with the following properties:

$$\begin{aligned} u_{0\varepsilon}(x) &\in C^1(\bar{\Omega}), \quad u_{0\varepsilon}(x) \geq \varepsilon, \quad u_{0\varepsilon_i}(x) \geq u_{0\varepsilon_j}(x) \text{ for } \varepsilon_i \geq \varepsilon_j, \\ u_{0\varepsilon}(x) &\rightarrow u_0(x) \text{ as } \varepsilon \rightarrow 0 \text{ uniformly in } \bar{\Omega}, \\ \frac{\partial u_{0\varepsilon}(x)}{\partial \nu} &= \int_{\Omega} k(x, y, 0) u_{0\varepsilon}^l(y) dy, \quad x \in \partial\Omega. \end{aligned} \quad (8)$$

Let us consider the following auxiliary problem:

$$\begin{cases} u_t = \Delta u + au^p \int_0^t u^q(x, \tau) d\tau - bu^m + b\varepsilon^m, & (x, t) \in Q_T, \\ \frac{\partial u(x, t)}{\partial \nu} = \int_{\Omega} k(x, y, t) u^l(y, t) dy, & (x, t) \in S_T, \\ u(x, 0) = u_{0\varepsilon}(x), & x \in \Omega, \end{cases} \quad (9)$$

where  $\varepsilon = \varepsilon_m$ . The notion of a solution  $u_\varepsilon$  for problem (9) can be defined in a similar way as in the definition 1.

**Theorem 1.** Problem (9) has a unique solution in  $Q_T$  for small values of  $T > 0$ .

**Proof.** Denote  $K = \sup_{\partial\Omega \times Q_1} k(x, y, t)$  and introduce an auxiliary function  $\psi(x)$  with the following properties:

$$\psi(x) \in C^2(\bar{\Omega}), \quad \inf_{\Omega} \psi(x) \geq \max\left(\sup_{\Omega} u_{0\varepsilon}(x), 1\right), \quad \inf_{\partial\Omega} \frac{\partial \psi(x)}{\partial \nu} \geq K \max(1, \exp(l-1)) \int_{\Omega} \psi^l(y) dy.$$

We put

$$w(x, t) = \exp(\alpha t) \psi(x),$$

where  $\alpha$  will be defined below.

To prove the existence of a solution for problem (9) we introduce the set

$$B = \{h(x, t) \in C(\bar{Q}_T) : \varepsilon \leq h(x, t) \leq w(x, t), \quad h(x, 0) = u_{0\varepsilon}(x)\}$$

and consider the problem

$$\begin{cases} u_t = \Delta u + a v^p \int_0^t v^q(x, \tau) d\tau - b u^m + b \varepsilon^m, (x, t) \in Q_T, \\ \frac{\partial u(x, t)}{\partial \nu} = \int_{\Omega} k(x, y, t) v^l(y, t) dy, (x, t) \in S_T, \\ u(x, 0) = u_{0\varepsilon}(x), x \in \Omega, \end{cases} \quad (10)$$

where  $v \in B$ . It is obvious,  $B$  is a nonempty convex subset of  $C(\bar{Q}_T)$ . By classical theory [23] problem (10) has a solution  $u \in C^{2,1}(Q_T) \cap C^{1,0}(\bar{Q}_T)$  for small values of  $T$ . Let us call  $A(v) = u$ , where  $v \in B$ , and  $u$  is a solution of problem (10). In order to show that  $A$  has a fixed point in  $B$  we verify that  $A$  is a continuous mapping from  $B$  into itself such that  $AB$  is relatively compact. Obviously, the function  $u(x, t) = \varepsilon$  is a subsolution of problem (10). Let us show that  $w(x, t)$  is a supersolution of problem (10) for suitable choice of  $\alpha > 0$  and  $T > 0$ .

Indeed,

$$\begin{aligned} w_t - \Delta w - a v^p \int_0^t v^q(x, \tau) d\tau + b w^m - b \varepsilon^m &\geq w_t - \Delta w - a w^p \int_0^t w^q(x, \tau) d\tau + b w^m - b \varepsilon^m \geq \\ &\geq \exp(\alpha t) [\alpha \psi(x) - \Delta \psi(x)] - a \exp(p\alpha t) \frac{\exp(q\alpha t) - 1}{q\alpha} \psi^{p+q} + b(\exp(m\alpha t) \psi^m(x) - \varepsilon^m) \geq 0 \end{aligned}$$

for  $(x, t) \in Q_T$  if

$$\alpha \geq \max \left\{ \frac{1}{q}, a \exp(1) \sup_{\Omega} \psi^{p+q-1}(x) + \sup_{\Omega} \frac{\Delta \psi(x)}{\psi(x)} \right\}, T \leq \frac{1}{(p+q)\alpha}.$$

On the boundary  $S_T$  we have

$$\begin{aligned} \frac{\partial w(x, t)}{\partial \nu} - \int_{\Omega} k(x, y, t) v^l(y, t) dy &\geq \exp(\alpha t) K \max(1, \exp(l-1)) \int_{\Omega} \psi^l(y) dy - \\ &- K \exp(l\alpha t) \int_{\Omega} \psi^l(y) dy \geq 0 \end{aligned}$$

for  $T \leq \frac{1}{\alpha}$ . The inequality

$$w(x, 0) - u_{0\varepsilon}(x) \geq 0$$

holds for  $x \in \Omega$ . Then  $w(x, t)$  is a supersolution of problem (10) and thanks to a comparison principle for problem (10)  $A$  maps  $B$  into itself.

Let  $G(x, y; t - \tau)$  denote the Green's function for a heat equation with homogeneous Neumann boundary condition. The Green's function has the following properties (see, for example, [24]):

$$\begin{aligned} G(x, y; t - \tau) &\geq 0, x, y \in \Omega, 0 \leq \tau < t, \\ \int_{\Omega} G(x, y; t - \tau) dy &= 1, x \in \Omega, 0 \leq \tau < t. \end{aligned} \quad (11)$$

It is well known that  $u(x, t)$  is a solution of problem (10) in  $Q_T$  if and only if for  $(x, t) \in Q_T$

$$\begin{aligned} u(x, t) &= \int_{\Omega} G(x, y; t) u_{0\varepsilon}(y) dy + \\ &+ \int_0^t \int_{\Omega} G(x, y; t - \tau) \left( a v^p(y, \tau) \int_0^{\tau} v^q(y, \sigma) d\sigma + b(\varepsilon^m - u^m(y, \tau)) \right) dy d\tau + \\ &+ \int_0^t \int_{\partial\Omega} G(x, \xi; t - \tau) \int_{\Omega} k(\xi, y, \tau) v^l(y, \tau) dy dS_{\xi} d\tau. \end{aligned} \quad (12)$$

We claim that  $A$  is continuous. In fact let  $v_k$  be a sequence in  $B$  converging to  $v \in B$  in  $C(\bar{Q}_T)$ . Denote  $u_k = A v_k$ . Then by (11) and (12) we see that

$$\begin{aligned}
 |u - u_k| &= \left| \int_0^t \int_{\Omega} G(x, y; t - \tau) \left\{ a \left( v^p(y, \tau) - v_k^p(y, \tau) \right) \int_0^{\tau} v^q(y, \sigma) d\sigma + \right. \right. \\
 &+ a v_k^p(y, \tau) \int_0^{\tau} \left( v^q(y, \sigma) - v_k^q(y, \sigma) \right) d\sigma - b \left( u^m(y, \tau) - u_k^m(y, \tau) \right) \left. \right\} dy d\tau + \\
 &+ \int_0^t \int_{\partial\Omega} G(x, \xi; t - \tau) \int_{\Omega} k(\xi, y, \tau) \left( v^l(y, \tau) - v_k^l(y, \tau) \right) dy dS_{\xi} d\tau \left| \leq \right. \\
 &\leq a T^2 \sup_{Q_T} |v^p - v_k^p| \sup_{Q_T} w^q + a T^2 \sup_{Q_T} |v^q - v_k^q| \sup_{Q_T} w^p + \\
 &+ \theta T \sup_{Q_T} |u - u_k| + K T |\Omega| \sup_{Q_T} |v^l - v_k^l|,
 \end{aligned}$$

where  $\theta = mb \max \left( \varepsilon^{m-1}, \sup_{Q_T} w^{m-1}(x, t) \right)$ ;  $T \leq \min \left\{ 1, \frac{1}{2\theta} \right\}$ . Now we can conclude that  $u_k$  converges to  $u$  in  $C(\bar{Q}_T)$  as  $k \rightarrow \infty$ .

The equicontinuity of  $AB$  follows from equation (12) and the properties of the Green's function (see, for example, [25]). The Ascoli – Arzelà theorem guarantees the relative compactness of  $AB$ . Thus we are able to apply the Schauder – Tychonoff fixed point theorem and conclude that  $A$  has a fixed point in  $B$  if  $T$  is small. Now if  $u_{\varepsilon}$  is a fixed point of  $A$ ,  $u_{\varepsilon} \in C^{2,1}(Q_T) \cap C^{1,0}(\bar{Q}_T)$  and it is a solution of problem (9) in  $Q_T$ . Uniqueness of the solution follows from a comparison principle for problem (9) which can be proved in a similar way as in the next section. Theorem 1 is proved.

Now, let  $\varepsilon_2 > \varepsilon_1$ . Then it is easy to see that  $u_{\varepsilon_2}(x, t)$  is a supersolution of problem (9) with  $\varepsilon = \varepsilon_1$ . Applying to problem (9) a comparison principle we have  $u_{\varepsilon_1}(x, t) \leq u_{\varepsilon_2}(x, t)$ . Using the last inequality and the continuation principle of solutions we deduce that the existence time of  $u_{\varepsilon}$  does not decrease as  $\varepsilon \rightarrow 0$ . Taking  $\varepsilon \rightarrow 0$ , we get  $u_M(x, t) = \lim_{\varepsilon \rightarrow 0} u_{\varepsilon}(x, t) \geq 0$  and  $u_M(x, t)$  exists in  $Q_T$  for some  $T > 0$ . We know that  $u_{\varepsilon}(x, t)$  is a solution of problem (9) in  $Q_T$  if and only if for  $(x, t) \in Q_T$

$$\begin{aligned}
 u_{\varepsilon}(x, t) &= \int_{\Omega} G(x, y; t) u_{0\varepsilon}(y) dy + \\
 &+ \int_0^t \int_{\Omega} G(x, y; t - \tau) \left( a u_{\varepsilon}^p(y, \tau) \int_0^{\tau} u_{\varepsilon}^q(y, \sigma) d\sigma + b \left( \varepsilon^m - u_{\varepsilon}^m(y, \tau) \right) \right) dy d\tau + \\
 &+ \int_0^t \int_{\partial\Omega} G(x, \xi; t - \tau) \int_{\Omega} k(\xi, y, \tau) u_{\varepsilon}^l(y, \tau) dy dS_{\xi} d\tau.
 \end{aligned} \tag{13}$$

Passing to the limit as  $\varepsilon \rightarrow 0$  in equation (13), we obtain by dominated convergence theorem

$$\begin{aligned}
 u_M(x, t) &= \int_{\Omega} G(x, y; t) u_0(y) dy + \\
 &+ \int_0^t \int_{\Omega} G(x, y; t - \tau) \left( a u_M^p(y, \tau) \int_0^{\tau} u_M^q(y, \sigma) d\sigma - b u_M^m(y, \tau) \right) dy d\tau + \\
 &+ \int_0^t \int_{\partial\Omega} G(x, \xi; t - \tau) \int_{\Omega} k(\xi, y, \tau) u_M^l(y, \tau) dy dS_{\xi} d\tau
 \end{aligned}$$

for  $(x, t) \in Q_T$ . Therefore,  $u_M(x, t)$  is a solution of problem (1)–(3). Let  $u(x, t)$  be any other solution of problem (1)–(3). Then by comparison principle from the next section  $u_{\varepsilon}(x, t) \geq u(x, t)$ . Taking  $\varepsilon \rightarrow 0$ , we conclude  $u_M(x, t) \geq u(x, t)$ . Now we proved the following local existence theorem.

**Theorem 2.** Problem (1)–(3) has a maximal solution in  $Q_T$  for small values of  $T$ .

### Comparison principle

**Theorem 3.** Let  $\bar{u}(x, t)$  and  $\underline{u}(x, t)$  be a supersolution and a subsolution of problem (1)–(3) in  $Q_T$  respectively. Suppose that  $\underline{u}(x, t) > 0$  or  $\bar{u}(x, t) > 0$  in  $Q_T \cup \Gamma_T$  if either  $\min(q, l) < 1$  or  $0 < p < 1$ . Then  $\bar{u}(x, t) \geq \underline{u}(x, t)$  in  $Q_T \cup \Gamma_T$ .

*Proof.* Suppose that  $\min(p, q, l) \geq 1$ . Let  $T_0 \in (0, T)$  and  $u_{0\varepsilon}(x)$  have the same properties as in (8) but only  $u_{0\varepsilon}(x) \rightarrow \underline{u}(x, 0)$  as  $\varepsilon \rightarrow 0$  uniformly in  $\bar{\Omega}$ . We can construct a solution  $u_M(x, t)$  of problem (1)–(3) with  $u_0(x) = \underline{u}(x, 0)$  in the following way:  $u_M(x, t) = \lim_{\varepsilon \rightarrow 0} u_\varepsilon(x, t)$ , where  $u_\varepsilon(x, t)$  is a solution of problem (9). To establish the theorem we will show that

$$\underline{u}(x, t) \leq u_M(x, t) \leq \bar{u}(x, t), (x, t) \in \bar{Q}_{T_0}. \quad (14)$$

We prove the second inequality in relations (14) only since the proof of the first one is similar. Let  $\varphi(x, \tau) \in C^{2,1}(\bar{Q}_{T_0})$  be a nonnegative function such that

$$\frac{\partial \varphi(x, t)}{\partial \nu} = 0$$

for  $(x, t) \in S_{T_0}$ . If we multiply the first equation in problem (9) by  $\varphi(x, t)$  and then integrate over  $Q_t$  for  $t \in (0, T_0)$ , we obtain

$$\begin{aligned} & \int_0^t \int_{\Omega} u_{\varepsilon\tau}(x, \tau) \varphi(x, \tau) dx d\tau = \\ & = \int_0^t \int_{\Omega} \left( \Delta u_\varepsilon(x, \tau) + a u_\varepsilon^p(x, \tau) \int_0^\tau u_\varepsilon^q(x, \sigma) d\sigma + b(\varepsilon^m - u_\varepsilon^m(x, \tau)) \right) \varphi(x, \tau) dx d\tau. \end{aligned}$$

Integrating by parts and using Green's identity, we have

$$\begin{aligned} & \int_{\Omega} u_\varepsilon(x, t) \varphi(x, t) dx \leq \int_{\Omega} u_\varepsilon(x, 0) \varphi(x, 0) dx + \\ & + \int_0^t \int_{\Omega} (u_\varepsilon(x, \tau) \varphi_\tau(x, \tau) + u_\varepsilon(x, \tau) \Delta \varphi(x, \tau)) dx d\tau + \\ & + \int_0^t \int_{\Omega} \left( a u_\varepsilon^p(x, \tau) \int_0^\tau u_\varepsilon^q(x, \sigma) d\sigma + b(\varepsilon^m - u_\varepsilon^m(x, \tau)) \right) \varphi(x, \tau) dx d\tau + \\ & + \int_0^t \int_{\partial\Omega} \varphi(x, \tau) \int_{\Omega} k(x, y, \tau) u_\varepsilon^l(y, \tau) dy dS_x d\tau. \end{aligned} \quad (15)$$

On the other hand,  $\bar{u}$  satisfies (15) with reversed inequality and with  $\varepsilon = 0$ . Set  $w(x, t) = u_\varepsilon(x, t) - \bar{u}(x, t)$ . Then  $w(x, t)$  satisfies

$$\begin{aligned} & \int_{\Omega} w(x, t) \varphi(x, t) dx \leq \int_{\Omega} w(x, 0) \varphi(x, 0) dx + \varepsilon^m b \int_0^t \int_{\Omega} \varphi(x, \tau) dx d\tau + \\ & + \int_0^t \int_{\Omega} w(x, \tau) (\varphi_\tau(x, \tau) + \Delta \varphi(x, \tau) - m b \theta_1^{m-1}(x, \tau)) \varphi(x, \tau) dx d\tau + \\ & + \int_0^t \int_{\Omega} \left( a \bar{u}^p(x, \tau) \varphi(x, \tau) \int_0^\tau q \theta_2^{q-1}(x, \sigma) w(x, \sigma) d\sigma \right) dx d\tau + \\ & + \int_0^t \int_{\Omega} \left( a p \theta_3^{p-1}(x, \tau) w(x, \tau) \varphi(x, \tau) \int_0^\tau u_\varepsilon^q(x, \sigma) d\sigma \right) dx d\tau + \\ & + \int_0^t \int_{\partial\Omega} \varphi(x, \tau) \int_{\Omega} k(x, y, \tau) l \theta_4^{l-1}(y, \tau) w(y, \tau) dy dS_x d\tau, \end{aligned} \quad (16)$$

where  $\theta_i(x, \tau)$ ,  $i = 1, 2, 3, 4$ , are some continuous functions between  $u_\varepsilon(x, t)$  and  $\bar{u}(x, t)$ . Note here that by hypotheses for  $k(x, y, \tau)$ ,  $u_\varepsilon(x, t)$  and  $\bar{u}(x, t)$ , we have

$$\begin{aligned} 0 \leq \bar{u}(x, t) \leq M, \quad \varepsilon \leq u_\varepsilon(x, t) \leq M, \quad (x, t) \in \bar{Q}_{T_0}, \\ 0 \leq k(x, y, t) \leq M, \quad (x, y, t) \in \partial\Omega \times \bar{\Omega} \times [0, T_0], \end{aligned} \quad (17)$$

where  $M$  is some positive constant. Then it is easy to see from (17) that  $\theta_1^{m-1}(x, \tau)$ ,  $\theta_2^{q-1}(x, \tau)$ ,  $\theta_3^{p-1}(x, \tau)$  and  $\theta_4^{l-1}(x, \tau)$  are positive and bounded functions in  $\bar{Q}_{T_0}$  and, moreover,  $\theta_1^{m-1}(x, \tau) \leq \max\{\varepsilon^{m-1}, M^{m-1}\}$ ,  $\theta_2^{q-1}(x, \tau) \leq M^{q-1}$ ,  $\theta_3^{p-1}(x, \tau) \leq M^{p-1}$ ,  $\theta_4^{l-1}(x, \tau) \leq M^{l-1}$ . Define a sequence  $\{a_n\}$  in the following way:  $a_n(x, t) \in C^\infty(\bar{Q}_{T_0})$ ,  $a_n(x, t) \geq 0$  and  $a_n(x, t) \rightarrow mb\theta_1^{m-1}(x, t)$  as  $n \rightarrow \infty$  in  $L^1(\bar{Q}_{T_0})$ . Now, we consider a backward problem given by

$$\begin{cases} \varphi_\tau + \Delta\varphi - a_n\varphi = 0, & (x, \tau) \in Q_t, \\ \frac{\partial\varphi(x, \tau)}{\partial\nu} = 0, & (x, \tau) \in S_t, \\ \varphi(x, t) = \psi(x), & x \in \Omega, \end{cases} \quad (18)$$

where  $\psi(x) \in C_0^\infty(\Omega)$  and  $0 \leq \psi(x) \leq 1$ . Denote a solution of problem (18) as  $\varphi_n(x, \tau)$ . Then by the standard theory for linear parabolic equations (see, for example, [25]), we find that  $\varphi_n(x, \tau) \in C^{2,1}(\bar{Q}_t)$ ,  $0 \leq \varphi_n(x, \tau) \leq 1$  in  $\bar{Q}_t$ . Putting  $\varphi = \varphi_n$  in inequality (16) and passing to the limit as  $n \rightarrow \infty$ , we infer

$$\begin{aligned} \int_{\Omega} w(x, t)\psi(x)dx \leq \int_{\Omega} w_+(x, 0)dx + \varepsilon^m b T_0 |\Omega| + \\ + \left\{ a(p+q)M^{p+q-1}T_0 + l|\partial\Omega|M^l \right\} \int_0^t \int_{\Omega} w_+(x, \tau)dx d\tau, \end{aligned} \quad (19)$$

where  $w_+ = \max(w, 0)$ ;  $|\partial\Omega|$  and  $|\Omega|$  are the Lebesgue measures of  $\partial\Omega$  in  $\mathbb{R}^{n-1}$  and  $\Omega$  in  $\mathbb{R}^n$  respectively. Since inequality (19) holds for every  $\psi(x)$ , we can choose a sequence  $\{\psi_n(x)\}$  converging in  $L^1(\Omega)$  to

$$\psi(x) = \begin{cases} 1, & \text{if } w(x, t) > 0, \\ 0, & \text{if } w(x, t) \leq 0. \end{cases}$$

Passing to the limit as  $n \rightarrow \infty$  in inequality (19), we obtain

$$\begin{aligned} \int_{\Omega} w_+(x, t)dx \leq \int_{\Omega} w_+(x, 0)dx + \varepsilon^m b T_0 |\Omega| + \\ + \left\{ a(p+q)M^{p+q-1}T_0 + l|\partial\Omega|M^l \right\} \int_0^t \int_{\Omega} w_+(x, \tau)dx d\tau, \quad t \in (0, T_0]. \end{aligned}$$

Applying now Gronwall's inequality, we have

$$\int_{\Omega} w_+(x, t)dx \leq \left( \int_{\Omega} w_+(x, 0)dx + \varepsilon^m b T_0 |\Omega| \right) \exp \left[ \left\{ a(p+q)M^{p+q-1}T_0 + l|\partial\Omega|M^l \right\} t \right]$$

for  $t \in (0, T_0]$ . Passing to the limit as  $\varepsilon \rightarrow 0$ , the conclusion of the theorem follows for  $\min(p, q, l) \geq 1$ . For the case  $p = 0$ ,  $\min(q, l) \geq 1$  we prove the theorem in the same way. If  $\min(q, l) < 1$  or  $0 < p < 1$  we can consider  $w(x, t) = \underline{u}(x, t) - \bar{u}(x, t)$  and prove the theorem in a similar way using the positiveness of a subsolution or a supersolution. Theorem 3 is proved.

*Remark.* For similar problem (1), (3), (4) with  $p = 0$  the authors of work [22] suppose in the comparison principle that  $\underline{u}(x, t) > 0$  or  $\bar{u}(x, t) > 0$  in  $Q_T \cup \Gamma_T$  if  $\min(q, m, l) < 1$ .



**Lemma 1.** Let  $u(x, t)$  be a solution of problem (1)–(3) in  $Q_T$ . Let  $u_0(x) \not\equiv 0$  in  $\Omega$  and  $m \geq 1$ . Then  $u(x, t) > 0$  in  $Q_T \cup S_T$ . If  $u_0(x) > 0$  in  $\bar{\Omega}$  and  $p < m < 1$  then  $u(x, t) > 0$  in  $Q_T \cup \Gamma_T$ .

*Proof.* Let  $u_0(x) \not\equiv 0$  in  $\Omega$  and  $m \geq 1$ . We denote

$$M = \sup_{Q_{T_0}} u(x, t),$$

where  $M$  is some positive constant;  $T_0 \in (0, T)$ . Now we put  $h(x, t) = u(x, t) \exp(\lambda t)$  with  $\lambda \geq bM^{m-1}$ . Then in  $Q_{T_0}$  we have

$$h_t - \Delta h = \exp(\lambda t)(\lambda u + u_t - \Delta u) \geq u \exp(\lambda t)(\lambda - bu^{m-1}) \geq 0.$$

Since  $h(x, 0) = u_0(x) \geq 0$ ,  $x \in \Omega$ , and  $u_0(x) \not\equiv 0$  in  $\Omega$ , by the strong maximum principle  $h(x, t) > 0$  in  $Q_{T_0}$ . Hence,  $u(x, t) > 0$  in  $Q_{T_0}$ . Let  $h(x_0, t_0) = 0$  in some point  $(x_0, t_0) \in S_T$ . Then according to theorem 3.6 of work [26] it yields  $\frac{\partial h(x_0, t_0)}{\partial \nu} < 0$ , which contradicts boundary condition (2).

Let  $u_0(x) > 0$  in  $\bar{\Omega}$  and  $p < m < 1$ . Then there exist  $\tau \in (0, T)$  and  $\varepsilon > 0$  such that

$$u(x, t) \geq \varepsilon \text{ in } \bar{Q}_\tau$$

and, moreover,  $u(x, t) \equiv \varepsilon_1 = \min \left( \varepsilon, \left[ \frac{a\tau\varepsilon^q}{b} \right]^{\frac{1}{m-p}} \right)$  is the subsolution of problem (1)–(3) in  $Q_{T_0} \setminus \bar{Q}_\tau$  with initial

function  $u(x, \tau)$  for  $t = \tau$  instead of initial datum (3). Putting  $\underline{u}(x, t) \equiv \varepsilon_1$  and  $\bar{u}(x, t) \equiv u(x, t)$  and arguing as in the proof of theorem 3, we get

$$u(x, t) \geq \varepsilon_1 \text{ in } \bar{Q}_{T_0} \text{ for any } T_0 \in (0, T).$$

Lemma 1 is proved.

As a simple consequence of theorem 3 and lemma 1, we get the following uniqueness result for problem (1)–(3).

**Theorem 4.** Let problem (1)–(3) have a positive in  $Q_T \cup \Gamma_T$  solution or a solution in  $Q_T$  either with non-negative initial data in  $\Omega$  for  $\min(p, q, l) \geq 1$  or with positive initial data in  $\bar{\Omega}$  under the conditions  $m \geq 1$  or  $p < m < 1$ . Then a solution of problem (1)–(3) is unique in  $Q_T$ .

Now we will prove the nonuniqueness of solution of problem (1)–(3) with  $u_0(x) \equiv 0$  for  $l < \min(1, m)$  or  $p + q < \min(1, m)$ . We note that problem (1)–(3) with  $u_0(x) \equiv 0$  has solution  $u(x, t) \equiv 0$ .

**Theorem 5.** Let  $u_0(x) \equiv 0$  and either  $l < \min(1, m)$  and

$$k(x, y_0, t_0) > 0 \text{ for any } x \in \partial\Omega \text{ and some } y_0 \in \partial\Omega \text{ and } t_0 \in [0, T) \quad (20)$$

or  $p + q < \min(1, m)$ . Then a maximal solution of problem (1)–(3)  $u_M(x, t) \not\equiv 0$  in  $Q_T$ .

*Proof.* As shown in theorem 2 a maximal solution  $u_M(x, t) = \lim_{\varepsilon \rightarrow 0} u_\varepsilon(x, t)$ , where  $u_\varepsilon(x, t)$  is some positive in  $\bar{Q}_T$  supersolution of problem (1)–(3). To prove the theorem we construct a subsolution  $\underline{u}(x, t) \not\equiv 0$  of problem (1)–(3) with  $u_0(x) \equiv 0$ . By theorem 3 we have  $u_\varepsilon(x, t) \geq \underline{u}(x, t)$  and therefore maximal solution  $u_M(x, t) \not\equiv 0$ .

At first let  $l < \min(1, m)$  and inequality (20) hold. To construct a subsolution we use the change of variables in a neighbourhood of  $\partial\Omega$  as in work [27]. Let  $\bar{x}$  be a point on  $\partial\Omega$ . We denote by  $\bar{n}(\bar{x})$  the inner unit normal to  $\partial\Omega$  at the point  $\bar{x}$ . Since  $\partial\Omega$  is smooth it is well-known that there exists  $\delta > 0$  such that the mapping  $\psi : \partial\Omega \times [0, \delta] \rightarrow \mathbb{R}^n$  given by  $\psi(\bar{x}, s) = \bar{x} + s\bar{n}(\bar{x})$  defines new coordinates  $(\bar{x}, s)$  in a neighbourhood of  $\partial\Omega$  in  $\bar{\Omega}$ .

Under the assumptions of the theorem, there exists  $\bar{t}$  such that  $k(x, y, t) > 0$  for  $t_0 \leq t \leq t_0 + \bar{t}$ ,  $x \in \partial\Omega$  and  $y \in V(y_0)$ , where  $V(y_0)$  is some neighbourhood of  $y_0$  in  $\bar{\Omega}$ .

Let  $\frac{1}{1-l} < \alpha \leq \frac{1}{1-m}$  for  $m < 1$  and  $\alpha > \frac{1}{1-l}$  for  $m \geq 1$ ,  $2 < \beta < \frac{2}{1-m}$  for  $m < 1$  and  $\beta > 2$  for  $m \geq 1$ . Assume that  $A > 0$ ,  $0 < \xi_0 \leq 1$  and  $0 < T_0 < \min(T - t_0, \bar{t}, \delta^2)$ . For points in  $\partial\Omega \times [0, \delta] \times (t_0, t_0 + T_0]$  of coordinates  $(\bar{x}, s, t)$  define



$$\underline{u}(\bar{x}, s, t) = A(t - t_0)^\alpha \left( \xi_0 - \frac{s}{\sqrt{t - t_0}} \right)_+^\beta$$

and extend  $\underline{u}$  as zero to the whole of  $\bar{Q}_\tau$  with  $\tau = t_0 + T_0$ . Arguing as in work [18] we prove that  $\underline{u}$  is the subsolution of problem (1)–(3) with  $u_0(x) \equiv 0$  in  $Q_\tau$ .

Now we suppose that  $p + q < \min(1, m)$ . Then it is easy to check that  $\underline{u}(x, t) = t^\gamma$  is the subsolution of problem (1)–(3) with  $u_0(x) \equiv 0$  in  $Q_\tau$  for small values of  $\tau$  if

$$\gamma > \max \left( \frac{2}{1 - (p + q)}, \frac{1}{m - (p + q)} \right).$$

Theorem 5 is proved.

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