

**ON SOLVABILITY TO PROBLEM FOR SYSTEM OF
HYPERBOLIC EQUATIONS WITH PIECEWISE CONSTANT
ARGUMENT OF GENERALIZED TYPE
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Consider on the domain $\Omega = [0, T] \times [0, \omega]$ a nonlocal problem for the system of hyperbolic equations with piecewise-constant argument of generalized type in the following form

$$\begin{aligned} \frac{\partial^2 u}{\partial t \partial x} &= A(t, x) \frac{\partial u}{\partial x} + B(t, x) \frac{\partial u}{\partial t} + A_0(t, x) \frac{\partial u(\gamma(t), x)}{\partial x} + \\ &+ C(t, x) u(t, x) + C_0(t, x) u(\gamma(t), x) + f(t, x), \end{aligned} \quad (1)$$

$$P(x) \frac{\partial u(0, x)}{\partial x} + S(x) \frac{\partial u(T, x)}{\partial x} = \varphi(x), \quad x \in [0, \omega], \quad (2)$$

$$u(t, 0) = \psi(t), \quad t \in [0, T], \quad (3)$$

where $u(t, x) = \text{colon}(u_1(t, x), \dots, u_n(t, x))$ is unknown vector function, the $n \times n$ matrices $A(t, x)$, $B(t, x)$, $C(t, x)$, $A_0(t, x)$, $C_0(t, x)$ and n vector function $f(t, x)$ are continuous on Ω ; $\gamma(t) = \zeta_j$ if $t \in [\theta_j, \theta_{j+1})$, $j = 0, N-1$; $\theta_j \leq \zeta_j \leq \theta_{j+1}$ for all $j = 0, 1, \dots, N-1$; $0 = \theta_0 < \theta_1 < \dots < \theta_{N-1} < \theta_N = T$, the $n \times n$ matrices $P(x)$, $S(x)$ and the n vector function $\varphi(x)$ are continuous on $[0, \omega]$, the n vector function $\psi(t)$ is continuously differentiable on $[0, T]$.

As well-known, the questions of solvability to boundary value problems for differential equations with piecewise constant argument are of great importance and relevance [1]. Differential equations with piecewise-constant argument of generalized type are introduced in the work [2]. Mathematical modeling of real processes often leads to differential equations with piecewise-constant argument of generalized type. This requires the development of novel approaches and methods for solving such problems.

In present communication we study a conditions of solvability to problem for system of hyperbolic equations with piecewise constant argument of generalized type (1)–(3). We develop methods and results in [3] to the nonlocal problem (1)–(3).

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References

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2. Akhmet M.U. Integral manifolds of differential equations with piecewise constant argument of generalized type. *Nonlinear Analysis*. **66** (2) (2007), 367–383.
3. Assanova A.T. On the solvability of a nonlocal problem for the system of Sobolev-type differential equations with integral condition. *Georgian Math. J.* **28** (1) (2021), 49–57.

**О ТОЧНЫХ РЕШЕНИЯХ ОДНОГО ДИФФЕРЕНЦИАЛЬНОГО УРАВНЕНИЯ
В ЧАСТНЫХ ПРОИЗВОДНЫХ ЧЕТВЕРТОГО ПОРЯДКА
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В работе [1] рассмотрено дифференциальное уравнение в частных производных

$$\omega \omega_{xxxx} + a \omega_t \omega_{xxx} + b \omega_x \omega_{xxt} + c \omega_{xx} \omega_{xt} = 0. \quad (1)$$

Однако при исследовании уравнения (1) не проанализирован случай, когда $b = -a, c = 0$. Находясь в данных условиях, получим уравнение

$$\omega \omega_{xxxx} + a(\omega_t \omega_{xxx} - \omega_x \omega_{xxt}) = 0. \quad (2)$$

Легко проверить, что уравнение (2) не допускает полярных разложений.