# ALGORITHMIC APPROACH TO LINEARIZATION OF SCALAR ORDINARY DIFFERENTIAL EQUATION 

D.A. Lyakhov ${ }^{1}$, V.P. Gerdt ${ }^{2}$<br>${ }^{1}$ National Academy of Sciences of Belarus, Belarus lyakhovda@gmail.com<br>${ }^{2}$ Joint Institute for Nuclear Research, Russia gerdt@jinr.ru

An ordinary differential equation (ODE) of the first order solved with respect to the derivative can be always linearized by a suitable point transformation. However, in this case the linearization procedure is not efficient since finding the linearizing transformation is as hard as solving the equation under consideration. For the second order ODEs the situation is different. In this case only equation of the form

$$
\begin{equation*}
y^{\prime \prime}+F_{3}(x, y)\left(y^{\prime}\right)^{3}+F_{2}(x, y)\left(y^{\prime}\right)^{2}+F_{1}(x, y) y^{\prime}+F(x, y)=0 . \tag{1}
\end{equation*}
$$

may be a candidate for linearization. Sophus Lie [1] designed the following linearizability criterion for equation (1): the equation is linerizable by a point transformation if and only if

$$
\begin{aligned}
& \left(F_{3}\right)_{x x}-2\left(F_{2}\right)_{x y}+\left(F_{1}\right)_{y y}=\left(3 F_{1} F_{3}-F_{2}^{2}\right)_{x}-3\left(F F_{3}\right)_{y}-3 F_{3} F_{y}+F_{2}\left(F_{1}\right)_{y}, \\
& F_{y y}-2\left(F_{1}\right)_{x y}+\left(F_{2}\right)_{x x}=3\left(F F_{3}\right)_{x}+\left(F_{1}^{2}-3 F F_{2}\right)_{y}+3 F\left(F_{3}\right)_{x}-F_{1}\left(F_{2}\right)_{x} .
\end{aligned}
$$

A similar criterion was designed for third- and forth-order ODEs [2, 3]. By applying the point transformation

$$
u=f(x, y), \quad t=g(x, y), \quad J=f_{x} g_{y}-f_{y} g_{x} \neq 0
$$

to a linear ODE of the $n$-th order (whose general form is determined by Laguerre's theorem):

$$
u^{(n)}(t)+\sum_{i=0}^{n-3} A_{i}(t) u^{(i)}(t)=0
$$

we obtain

$$
\begin{equation*}
y^{(n)}(x)+\frac{P\left(y^{(n-1)}, \ldots, y^{\prime}\right)}{J\left(g_{x}+g_{y} y^{\prime}\right)^{n-2}}=0 \tag{2}
\end{equation*}
$$

Here the coefficients of polynomial $P$ are differential polynomials in $f, g$. The formula (2) defines the form of an equation to be a candidate for linearization.

Now one asks whether a given ODE of the rational form solved with respect to the highest order derivative

$$
y^{(n)}(x)+\frac{M\left(y^{(n-1)}, \ldots, y^{\prime}\right)}{N\left(y^{(n-1)}, \ldots, y^{\prime}\right)}=0
$$

can be linearized by a point transformation. In other words, whether there exist functions $f, g$ such that the equality

$$
\frac{P\left(y^{(n-1)}, \ldots, y^{\prime}\right)}{J\left(g_{x}+g_{y} y^{\prime}\right)^{n-2}}=\frac{M\left(y^{(n-1)}, \ldots, y^{\prime}\right)}{N\left(y^{(n-1)}, \ldots, y^{\prime}\right)}
$$

of rational functions in $\left(y^{(n-1)}, \ldots, y^{\prime}\right)$ holds. The last equality is equivalent to the polynomial one

$$
P\left(y^{(n-1)}, \ldots, y^{\prime}\right) N\left(y^{(n-1)}, \ldots, y^{\prime}\right)-M\left(y^{(n-1)}, \ldots, y^{\prime}\right) J\left(g_{x}+g_{y} y^{\prime}\right)^{(n-2)}=0 .
$$

in $\left(y^{(n-1)}, \ldots, y^{\prime}\right)$. Since any polynomial is identically zero if and only if its coefficients are zero ones, the linearizability check is reduced to solvability of the overdetermined system of nonlinear
partial differential equations (PDEs). In addition to the last system one more equation must be taken into account. This equation provides dependence of the functions $A_{i}(t)$ on $t$ only:

$$
\left(A_{i}(x, y)\right)_{x} g_{y}-\left(A_{i}(x, y)\right)_{y} g_{x}=0
$$

The consistency of any polynomially-nonlinear PDE system can be verified algorithmically by using the differential Thomas decomposition [4]. In doing so, the unknown functions are $f, g, A_{i}$ and their arguments are $(x, y)$.

The suggested linearizability test is rather simple and efficient. It is implemented in Maple and can be downloaded at: http://www.lyakhov.com.

For high-order ODEs, their linearizability is quite exceptional and its verification may need a large volume of symbolic algebraic computation. By this reason it makes sense to throw away apparently inapplicable cases. Thus, to admit linearization, the Lie symmetry algebra of point symmetries for an ODE must have dimension that is not less than the dimension of the symmetry algebra for a linear ODE of the same order. In other words, the dimension of symmetry algebra for the linearizable equation must be strictly higher than the order of the equation. It should be noted that the dimension of Lie symmetry algebra of the infinitesimal transformations can be algorithmically determined without integration of the determining equations [5].

It is remarkable that the second-order ODEs are linearizable if and only if their symmetry algebra is of maximally possible dimension equal to 8 [6]. As to higher order ODEs, their linearizability can be detected by inspection of the abstract Lie symmetry algebra that can also be found without integration of the determining equations [7].

Remark. Apart from ODEs with polynomial coefficients, the suggested algorithmic approach is also applicable to some cases when the coefficients of an ODE include elementary functions of the independent variable or/and also special functions defined by algebraic differential equations. Furthermore, our approach can be readily generalized to systems of ODEs $[8,9]$.

## References

1. Ibragimov N.H. Elementary Lie group analysis and ordinary differential equations. New York: Wiley, 1999.
2. Ibragimov N. H., Meleshko S. V. Linearization of third-order ordinary differential equations by point and contact transformations // Journal of Mathematical Analysis and Applications. 2008. V. 308. P. 266289.
3. Ibragimov N.H., Meleshko S.V., Suksern S. Linearization of fourth-order ordinary differential equations by point transformations // Journal of Physics A: Mathematical and Theoretical. 2008. 41, 23. 235206 ( 19 pp ).
4. Bachler T., Gerdt V., Lange-Hegermann M., Robertz D. Algorithmic Thomas decomposition of algebraic and differential systems // Journal of Symbolic Computation. 2012. V.47, no. 10. P. 1233-1266.
5. Schwarz F. An algorithm for determining the size of symmetry groups // Computing. 1992. V.49, no. 2. P. 95-115.
6. Ibragimov N. H. Experience in group analysis of ordinary differential equations // Mathematics and Cybernetics. 1991. No. 7 [In Russian].
7. Reid G. J. Finding abstract Lie symmetry algebras of differential equations without integrating determining equations // European Journal of Applied Mathematics. 1991. 2, 4. P. 319-340.
8. Bagderina Y. Y. Linearization criteria for a system of two second-order ordinary differential equations // Journal of Physics A: Mathematical and Theoretical. 2010. V.43. 465201 (14 pp).
9. Suksern S., Sakdadech N. Criteria for System of Three Second-Order Ordinary Differential Equations to Be Reduced to a Linear System via Restricted Class of Point Transformation // Applied Mathematics. 2014. V. 5. P. 553-571.
