QUALITY MANAGEMENT UNDER UNCERTAINTY
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Abstract. The questions of “general quality management” specified in ISO 9001:2000 are under consideration. An approach based on modeling by precedence and intended for controlling quality management systems with an indeterminate deviation is proposed.

Introduction
An increased interest to new information technologies of quality management (QM) has been observed recently. This has been determined by at least two factors: on the one hand, ever-growing competition and corresponding market pretensions to a manufacturer; and on the other hand, expansion of the ISO 9000 standards, which have demanded new forms and methods of resource mobilization, control mechanism reorganization, business structure rebuilding etc.

Basic management methods, formed in the 60-s – 70-s of the past century, can’t by themselves provide an effective control of organizations nowadays. This is caused by the fact that most organizations represent complex man-machine systems. Their functioning depends on a great number of weakly formalizable dynamic factors. As a rule, there’s no possibility to reveal and promptly characterize all these factors a priori. As a result, QM has to be implemented under uncertainty. In this case QM is realized on the base of current observations and turns into on-line correction of controlling in response to functioning quality discord. The need to automatize this process dictates the necessity of advancement of the existing models and methods and the development of new ones. To solve these problems we need to use present-day mathematical theories including the theory of artificial intelligence.

One of the approaches to problem solving is proposed in the paper.

Quality management in the ISO 9000 standards
According to the ISO standard (ISO 9000 family standard, 2000 edition) QM represents an interrelated procedures system, “serving” a network of processes which define final product quality. QM implies complex solution of such problems as: planning, assurance, control and improvement of quality of processes, which form the so-called E. Deming’s control cycle (or “p-d-c-a”) (fig. 1). Each stage of the “p-d-c-a” cycle is based on the following subsystems deployment: acquisition, registration, analysis and generalization of appropriate data [1-3].

The first stage aims at creation of a functional model of organization business-processes. The model is intended for the formal description of business-process structure (of constituting subprocesses and their relations), and also of all information flows and material flows circulating in it. This stage has been well worked out. In particular for the model-building, a methodology for process network description basing on the IDEF0 standard has been developed [2].

The second and the third stages have been also well worked out in the practice of organizations of Belarus, Russia and other countries[4].

The fourth stage is connected with efficient managing decision-making (corrective and preventive actions) on the base of feedback. Unlike the others it hasn’t had essential scientific and methodological work out. Most often this process isn’t automatized and entirely realized by manual labour. That’s why management today is more an art than a formalized and well-grounded process. According to the seventh of the QM principles corrective and preventive actions should be based on “factual data”. Development of this mechanism’s successful model is the missing link in the “through” QM methodology.

Conceptually managing decision making mechanism lies in the following: management efficiency used depends on the process state. The process is implemented as a transition into one or another process state. In general change of process state demands new managements. Decision making is realized on the base of a current process state assessment. The process state is defined by set of internal conditions (those connected with the manufacturing system directly) and external conditions (connected with system functioning environment). Let’s call a set of these conditions a situation. It is characterized by the set of measurable parameters (situation description) being informational state vector.
Under the unpredictable process change condition situational management can be used for decision making:
- current state monitoring and identification of the moment of transition to a new state;
- making new decisions which are adequate to the current situation.

QM has at least two interconnected and subordinate contours of management:
- “general quality management” – first level loop, expressed as QMS requirements (ISO 9001:2000);
- “local quality control” – second level loop, is specific in the methods, approaches, tools.

“General quality management” loop purpose is effectiveness assurance in general. It realizes integrated approach to quality management irrespective of the type of output product, life cycle peculiarities, organization structure, property type etc. The sphere of the loop application is network of processes constituting organization business process. According to ISO 9001:2000 general management is realized on the following levels:
- strategical management (which is realized as requirements of the clause 5 “Management responsibility”);
- resource management (realized as requirements of the clause 6 “Resource management”);
- operative management or controllable conditions assurance (realized as requirements of the clause 7 “Product realization”);
- measurement, analysis and improvement (realized as requirements of the clause 8 “Measurement, analysis and improvement”);

“Local quality control” loop is not specified in ISO 9001:2000 and that’s why it is not restricted in methods, approaches, tools. The loop’s purpose is assurance of the whole business-process quality and its particular subprocesses. It is aimed at the organization competitiveness enhancement and implements an integrated approach to the quality management under particular conditions, determined by internal factors as well as external ones.

“General quality management” loop is more formalized. It is more capable of automatization and can be first of all considered as research object.

**Quality management model by precedence**

The role of the general quality management is to assure (in terms of given criteria) the conformance to ISO 9001:2000 requirements of clauses 5-8 through the whole business-process.

It is assumed that for each particular requirement expert scores are given, which characterize its quality of conformance. Scores are measured in some scale and can be defined (e.g. on the ground of audit
findings) in any current moment of manufacturing process. There is a limit defined for each requirement, which indicates acceptable deviation from the maximal score.

According to the typical situation we assume that process transition into a new state can occur in any random point of time and is determined by a set of unknown uncontrollable factors. As a consequence there’s no possibility to identify the reasons.

Process state change as a rule violates a degree of conformity to some requirements. That’s why appropriate managing actions should be taken during system functioning. They are determined by either observed process dynamics or are based on forecasting or can be of the following character:

- preventive (preventive actions),
- corrective, i.e. be as an answer to occurred changes (corrective actions or corrections),
- character of planned process and/or product improvement (improving actions).

As a result the task of management (on a general quality management level) can be reduced to the tracking task. The essence of this task is real-time change of process state in response to nonconformity to ISO 9001:2000 requirements.

This task can be formulated in the following way. Let $P$ is a complex process of general quality management; $X$ – a set of its acceptable states; $C(X) = \{c:X\to X\}$ – a set of acceptable control actions (corrections); $R$ – a set of ISO 9001:2000 requirements, corresponding to “general quality management” loop (fig.2); $Q:R\times X\to [0,N]$, $N<\infty$ – quality assessment of compliance of requirements $r$ from $R$ in different states $x$ from $X$.

It is required to realize the following equation $c^*:X\to X$, $c^*(x)\in \{x\} \cup \{c(x),c\in C\}$, which for every $x$ from $X$ assures the following terms

$$Q(r,c^*(x))\geq a_r, \forall r\in R$$

where $\{a_r\}_{r\in R}$ is a set of given parameters.

The task solution is in creation of local efficient complex control action (control) in the form of sequence of corrections, adequate to the manufacturing process dynamics. Under unpredictable dynamics condition it is reasonable to use control based on a current state observation and analysis.
Fig. 2 Segment of “general quality management” model – decomposition of one of the four “resource management” control processes (clause 6 ISO 9001:2000 “Resource management”; indexes correspond to numbers of requirements’ points)

Thereby two main subtasks arise:
- detection of system functional “discord”, i.e. violation of term (1) (discord problem),
- automatic choice of locally efficient correction, restoring term (1) (problem of choice).

While developing approaches to these tasks solution we can proceed from the following “general quality management” loop peculiarities:
- effectiveness of the control loop (of management system operation in the whole) is conditioned by a great variety of weakly formalizable factors (fig.2);
- relation between effectiveness and these factors is weakly formalizable, what along with the previous peculiarity makes the effectiveness estimation “poor”, i.e. low-informative;
- loop is specified in ISO 9001:2000 [3], what determines general management mechanism stability and allows to use the accumulated experience.

Stated peculiarities determine appropriateness of usage of fuzzy formalization methods, based on practical experience [5].
Most often experience is represented by examples of successful manufacturing situations with corresponding corrections indication. If that’s the case, discord situation identification and adequate correction selection are based on modeling by precedence: comparison of the current situation with the known examples and decision making, corresponding to a similar example.

Modeling by precedence is realized in the framework of the mathematical theory of pattern recognition. Primary task is to build informative space of attributes to describe set X of acceptable process states.

Here the task of detection of observed informative parameters, which reflect general management quality, arises. The problem lies in the usually unknown relating mechanism between observed process parameters and type of adequate correction. This does not allow to identify acceptable subset of indirect attributes. That’s why it is suggested to use general management efficiency-performance factors described as ISO 9001:2000 requirements (clauses 5 to 8) as attributes for situation description.

Then state \( x \in X \) is described by vector of the following type \((x_1, \ldots, x_N)\), including the four attribute groups:

1. \( x_1, \ldots, x_{N_1} \) - attributes, corresponding to the clause “Management responsibility”;
2. \( x_{N_1+1}, \ldots, x_{N_2} \) – attributes, corresponding to the clause “Resource management”;
3. \( x_{N_2+1}, \ldots, x_{N_3} \) – attributes, corresponding to the clause “Product realization”;
4. \( x_{N_3+1}, \ldots, x_N \) - attributes, corresponding to the clause “Measurement, analysis and improvement”.

Tolerance region of attribute \( x_i, 1 \leq i \leq 82 \) is defined by set of acceptable numerical scores of \( i \)-attribute. Scores characterize quality of requirement compliance and are usually defined by finite number of integral values.

Let \( X_0 = \{x_i^o\}_{i=1}^{l=K} \) is a set of known states, used as an examples. Initial information is \( T = \{< (m_{ij}, \ldots, m_{iN}), a_i> \}_{i=1,2,\ldots,l} \). Here \( m_{ij} \), \( 1 \leq i \leq K, 1 \leq j \leq 82 \) is a numerical score, characterizing degree of conformity to \( j \)-requirement in state \( x_i^o \), and \( a_i \) is a description of corresponding \( x_i^o \) corrections. As each clause of “general management” requirements has its own corresponding control, \( a_i \) is like \((a_{i1}, a_{i2}, a_{i3}, a_{i4})\), where \( a_{i1}, a_{i2}, a_{i3}, a_{i4} \) is control according to each of four clauses. Set \( A_j = \{a_{ij}, \ldots, a_{ijTj}\}, 1 \leq j \leq 4 \) of acceptable corrections is formed by experts. For states \( x_i^o \), which don’t demand corrections, it is assumed that \( a_i = (0,0,0,0) \).

In the context of disorder problem set \( X \) of acceptable states allows splitting into 2 classes

\[
X = X^+ \cup X^-.
\] (2)

Here \( X^+ \) is subset of normal states, and \( X^- \) - subset of discord states. The first one corresponds to a set of desirable process states when no corrections are needed. The second corresponds to set of states which do not conform to the required quality and demand appropriate corrections.

Disorder problem is solved by constant manufacturing process monitoring. Direct testing of term (1) for the current state \( x \in X \) is rather time-consuming task. Two-level solution of disorder problem is proposed: - manufacturing process current estimation on the basis of rather simple heuristic algorithms (current monitoring) and - direct testing of term (1) (total audit).

One of possible approaches to monitoring consists in classification of the current state with respect to splitting (2). Thereto we can use recognition with training. On stage of training to class \( X^+ \) refer \( x_i^o \in X_0 \), for which \( a_i = (0,0,0,0) \), and to class \( X^- \) - all other states.

The decision rule is formed in the following way. On the base of expert analysis each attribute group \( \{x_1, \ldots, x_{30}\}, \{x_{31}, \ldots, x_{40}\}, \{x_{41}, \ldots, x_{62}\}, \{x_{63}, \ldots, x_{82}\} \) is associated with one or more integral attributes. They provide rough (but easily calculated) estimate of requirements’ feasibility of appropriate ISO clause in the whole.

Hence, at any current point of manufacturing process all the “general management” loop requirements should be fulfilled, \( X^- \) consists of elements, which attribute values are sufficiently close to the maximum. For \( X^+ \) elements this condition is untrue at least for one of the attributes. Thus, for the classification of the current state \( x \in X \) with respect to splitting (2), acquired at the training stage, we can use e.g. “nearest neighbor” method scheme with proximity function \( \mu \):

\[
\mu((x_1, \ldots, x_n), (y_1, \ldots, y_n)) = \max_{i=1,\ldots,n} \{ |x_i - y_i| \}.
\]

Precise diagnostics of discord situation (total audit) is held in certain specified time periods or in emergency cases, indicating flat violation of general management maintenance.

In order to solve the problem of choice, recognition with training can be used.
As “general management” loop is split into 4 independent clauses, and realization of each demands its own corrections, it is proposed to consider individual problem of choice for each of the clauses. Totality of corrections obtained makes up an integrated managing decision on “general management” provision.

At training stage 4 splittings of a set $X^-$ into clusters of similar situations are formed: according to attribute groups $\{x_{11}, \ldots, x_{30}\}$, $\{x_{31}, \ldots, x_{40}\}$, $\{x_{41}, \ldots, x_{62}\}$ и $\{x_{63}, \ldots, x_{82}\}$. Each of them is conditioned that situations in one cluster are to have corresponding equal control. Possibility of such splitting construction is conditioned by the following factors. Effectiveness of the control action depends on system state. Manifestations of different system states in their diversity exceed greatly the number of acceptable controlling decisions. While the latter have a certain stability, and as a result one and the same control is effective in rather close situations. Splitting reduces to clusterization with the outer aim without a tutor. In order to solve it we can use the “dynamic nuclei” method scheme.

The choice of correction in current state $x \in X^-$ is reduced to its subsequent classification with respect to each of the four obtained splittings of $X^-$. According to the results of the classification with respect to one or another splitting control action, which assures conformance to corresponding group of requirements is chosen. Totality of solutions, obtained after these classifications, makes up the solution of the problem of choice.

Conclusion

The two control loops in a quality system condition existence of the two types of manufacturing process control problems: control tasks on the general management level and control tasks on the engineering-technical personnel level. Each of them can be formulated as a tracking task, which aims at usage of optimal/suboptimal (with respect to given efficiency criteria and on given set of allowable alternatives) control action at any current stage of manufacturing process. As each loop has its own “bottlenecks”, efficiency criteria and initial data, the tasks require different solution techniques. However, general decision-making scheme by precedence is applicable in both cases. At the engineering-technical control level it can be used under conditions, when reason for discord from the objective can’t be identified and choice of control action is realized in dialog mode on the basis of special analysis of the current state. Observed product quality figures in this case can be used to describe current manufacturing state.

References